

SAT-based Reasoning Techniques for LTL over Finite and Infinite Traces

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Linear Temporal Logic

- ▶ First introduced to Computer Science by A. Pnueli in 1977
- ▶ Formal verification (over infinite traces: LTL)
- ▶ AI (over finite traces : LTL_f)

Linear Temporal Logic

Syntax for LTL and LTL_f

$$\phi ::= p \mid \neg\phi \mid \phi \wedge \phi \mid \phi \vee \phi \mid X\phi \mid \phi U\phi \mid \phi R\phi \mid G\phi \mid F\phi;$$

- ▶ $\neg(\phi_1 U\phi_2) = \neg\phi_1 R\neg\phi_2$
- ▶ $\neg X\phi = N\neg\phi$ (Weak Next), for LTL_f only
- ▶ $F\phi = ttU\phi$
- ▶ $G\phi = ffR\phi$

Linear Temporal Logic

Semantics for LTL (LTL_f),

- ▶ Let ξ be a trace with $|\xi| = n$ ($n > 0$)
 - ▶ $\xi \models p$ if $p \in \xi[0]$
 - ▶ $\xi \models \neg\phi$ if $\xi \not\models \phi$
 - ▶ $\xi \models \phi_1 \wedge \phi_2$ if $\xi \models \phi_1$ and $\xi \models \phi_2$
 - ▶ $\xi \models X\phi$ if $n > 1$ and $\xi_1 \models \phi$
 - ▶ $\xi \models \phi_1 U \phi_2$ if (1) there is $0 \leq i < n$ s.t. $\xi_i \models \phi_2$ and (2) for every $0 \leq j < i$ it holds $\xi_j \models \phi_1$.
- ▶ LTL semantics: $n = \infty$
- ▶ LTL_f semantics: $n < \infty$

LTL vs. LTL_f

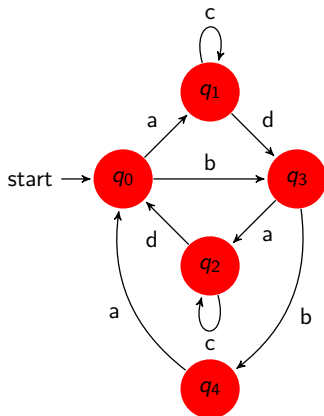
- ▶ Xtt is always true in LTL, but not in LTL_f
- ▶ $(a \wedge Xtt) \not\equiv a$ in LTL_f
- ▶ $\neg X\phi \neq X\neg\phi$ ($\neg X\phi = N\neg\phi$)
- ▶ $GX\phi$ is never satisfiable in LTL_f

This Talk

- ▶ Present an on-the-fly approach to construct automata by SAT solvers
- ▶ Show one of its applications to solve LTL_f satisfiability checking problem

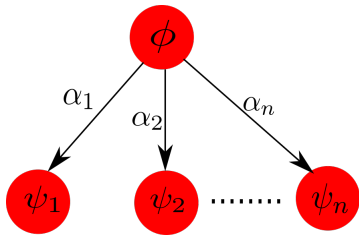
LTL(f) to Automata

$\phi \implies$



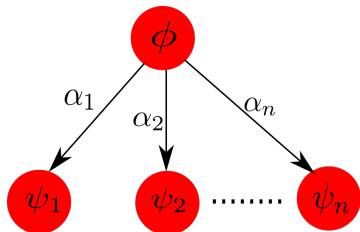
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$$\phi \iff \forall_i (\alpha_i \wedge X(\psi_i))$$



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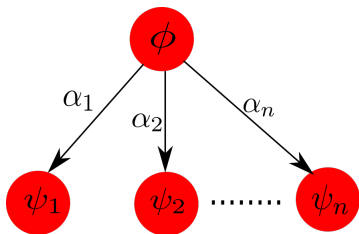
$$\phi \iff \bigvee_i (\alpha_i \wedge X(\psi_i))$$



Bottleneck: $\phi \iff \bigvee_i (\alpha_i \wedge X(\psi_i))$ is expensive!

LTL(_f) to Automata

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Question: Is it possible to generate ONE successor at one time (on the fly)?

neXt Normal Form (XNF)

If considering the temporal subformulas as atoms, an $LTL(f)$ formula ϕ becomes a Boolean formula.

We say ϕ is in XNF iff only X/N subformulas can be its atom.

neXt Normal Form (XNF)

Example

- ▶ $(a \vee bUc) \wedge cRd$ is not in XNF
- ▶ $(a \vee c \vee b \wedge X(bUc) \wedge d \wedge (c \vee X(cRd)))$ is in XNF

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3. Take $xnf(\phi)$ as the input of a SAT solver
4. SAT solver may return: $\{a, \neg b, X(aUb), X(\neg bU\neg a)\}$
 - ▶ A transition in the automaton is $\phi \xrightarrow{a \wedge \neg b} (aUb) \wedge (\neg bU\neg a)$

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To construct the whole automaton, just do enumeration!

LTL_f Satisfiability Checking

Problem

Given an LTL_f formula ϕ , is there a finite trace ξ s.t. $\xi \models \phi$?

- ▶ Fa is satisfiable;
- ▶ $Fa \wedge G\neg a$ is unsatisfiable;

Determining Final State

Introduce a new atom *Tail* to associate with X

$$X\psi \Longrightarrow \neg Tail \wedge X\psi$$

Example

- ▶ $b \vee X(aUb) \Longrightarrow b \vee \neg Tail \wedge X(aUb)$
- ▶ $XX\phi \Longrightarrow \neg Tail \wedge X(\neg Tail \wedge X\phi)$

Determining Final State

Theorem

ϕ is a final state iff $Tail \wedge xnf(\phi)$ is satisfiable (Boolean formula).

BLSC: Basic SAT-based Checking

Algorithm 1 BLSC: Basic on-the-fly LTL_f Satisfiability Checking

Require: An LTL_f formula ϕ .

Ensure: SAT or UNSAT.

- 1: **if** $Tail \wedge xnf(\phi)$ is satisfiable **then**
 - 2: **return** SAT;
 - 3: **end if**
 - 4: Add ϕ into $block_list$;
 - 5: Let $\psi = xnf(\phi) \wedge \neg X(block_list)$;
 - 6: **while** ψ is satisfiable **do**
 - 7: Let t be a propositional assignment for ψ ;
 - 8: Let $\phi' = \bigwedge\{\theta \mid X\theta \in t\}$;
 - 9: **if** BLSC (ϕ') returns SAT **then**
 - 10: **return** SAT;
 - 11: **end if**
 - 12: **end while**
 - 13: **return** UNSAT;
-

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- ▶ Computing states via SAT solvers does not save the space!
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 - ▶ BLSC leverages the satisfiability from SAT solvers
 - ▶ BLSC discards the unsatisfiability from SAT solvers

CDLSC: Conflict-Driven Checking

$Tail \wedge xnf(\phi)$ is UNSAT

\implies

there is ψ s.t. $\psi \subseteq \phi^1$ and $Tail \wedge xnf(\psi)$ is still unsatisfiable
(UNSAT core)

¹Consider ϕ have the form of $\bigwedge \phi_i$

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- ▶ ψ can be provided by a SAT solver
- ▶ ψ represents a set of states that **cannot reach** a final state in 0 step

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CDLSC: Conflict-Driven Checking

Conflict Sequence: $\mathcal{C} = C_0, C_1, C_2, \dots, C_k (k \geq 0)$

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- ▶ Guided search:
 - ▶ ψ is known in some $C_i \implies$ a next state of ψ not in C_i is preferred: **$xnf(\phi) \wedge \neg X C_i$**
 - ▶ Otherwise, check final state: **$Tail \wedge xnf(\psi)$**

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 - ▶ Otherwise, check final state: $\text{Tail} \wedge \text{xf}(\psi)$
- ▶ Unsatisfiability check: $\bigcap_{0 \leq j \leq i} C_j \subseteq C_{i+1}$

Evaluation

- ▶ Benchmarks: 7446 LTL-as- LTL_f formulas in previous work
- ▶ Platform: Rice Davinci cluster
- ▶ Timeout: 60 seconds for each instance
- ▶ Tools:
 1. Aalta-finite [LZPVH14]
 2. Aalta-infinite [LZPV15]
 3. ltl2sat [FG16]
 4. nuXmv (IC3+KLIVE) [CCDGMMMRT14]
 5. BLSC
 6. CDLSC

Evaluation

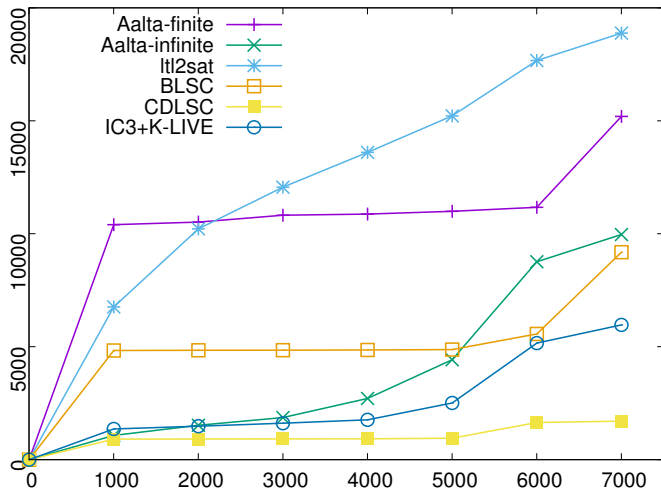


Figure 1: Cactus plot for LTL_f Satisfiability Checking on LTL-as- LTL_f Benchmarks.

Beyond Satisfiability Checking

- ▶ On-the-fly Synthesis for LTL over finite traces [AAAI2019]
- ▶ Satisfiability checking for LTL over infinite traces[FMSD 2019]
- ▶ Synthesis for LTL over infinite traces?
- ▶ On-the-fly LTL model checking?
- ▶ Extension to word-level?

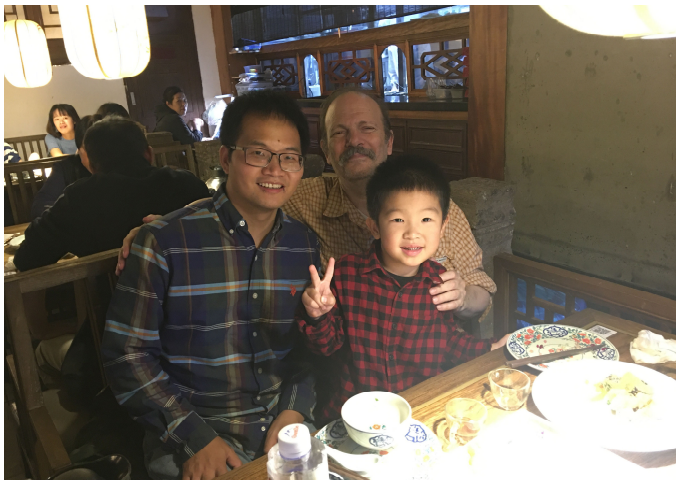


Figure 2: Shanghai, Oct. 2019.

Hope to see you again VERY soon!